Power Management System For Isolated Hybrid PV/WT/PEMFC Power Generation

Rupendra Kumar Pachauri, Yogesh K. Chauhan, Safia A. Kazmi

Abstract: In this article, an energy source for standalone power generating scheme is incorporated into a hybrid wind turbine (WT)/photovoltaic (PV)/fuel cell (FC). WT and PV systems are the system's main power generator, while the FC system is used as an energy backup source. For the suggested scheme, a general power management strategy is intended to handle the power flows among the various sources of energy. Using MATLAB/Simulink, a simulation model for the hybrid power scheme was developed. The system efficiency is explored using transient assessment of system parameters under distinct load demand energy situations.

Index Terms: Blade pitch angle, fuel cell, hybrid power generation, photovoltaic system, power management, renewable energy, wind turbine.

1. INTRODUCTION

Due to its multiple advantageous properties like the ecological, financial, etc., renewable energy (RE) sources are becoming extremely demanding. Reliability is another important aspect where, the hybrid power generation is gaining more popularity [1]. The conventional electric power is generated using fossils fuels (hybrid or non-hybrid systems), but the rising fuel prices, scarcity and difficulties of transportation, have forced to search more energy sources [2]. In different apps, the WT based conversion scheme and PV technologies are frequently used [3]. Nowadays, wind power is one of the increasing RE sources and is used for several reasons [4]. The PV cell transforms solar energy directly into power but the PV system's energy conversion efficiency is small [5-7]. The PV system uses residential appliances, business machinery, lighting and air conditioning for all kinds of houses, primarily as a grid-connected energy [8]. PV panels and construction roofs can be installed on the floor. For various locations, the climatic situations such as sun irradiance, wind speed, variable temperature are different which reduce the performance of the system for electric power production from PV and WT system. For reliability point of view, hybrid power generation concept is more acceptable now-a-days [9]. For this purpose, PV and WT are considered as a primary sources and FC, storage devices used as power backup sources. FC is a static noise less system, eco-friendly and high power density system; also it is used for both mobile and stationary applications [10].

The authors of [11] proposed a concept with extensive studies to integrate more than one RE sources e.g. solar, wind and hydrogen for power generation. In [12], the authors gave a concept on the hybrid power generation. The dynamic conduct of an island system with a hybrid energy scheme will be analyzed and the impact on the transient conduct of the structure of the multiple hybrid energy system working methods examined. The writers of [13] reported on a hybrid power generation concept that includes RE sources such as wind, PV and battery systems. With grid inclusion, the efficiency of the scheme proposed was explored. The authors in [14], proposed a concept on hybrid power system with the combination of RE sources e.g. wind, hydropower and PV system etc. The transient analysis of the system is investigated on the customer variable load. In [15], a hybrid energy generation system WT/PV/FC was intended and examined. In this setup, a FC stack, electrolyzer and H2 storage tank are used as an energy storage system. The performance of the MATLAB/Simulink based system is investigated under dynamic performance. The authors of [16] discussed a concept on the hybrid PV/FC/battery power generation and power management scheme is also used. The authors of [17] proposed a system which is an integration of RE sources, such as FC and battery system for power generation. To investigate with a smart power management scheme, the writers of [18] suggested a grid-connected WT/PV hybrid energy scheme. The findings of the simulation confirmed the suggested scheme of hybrid generation. The authors of [19] proposed a concept on the hybrid WT/FC and a super capacitor. A general approach to energy monitoring was developed to monitor energy flow. A hybrid system mathematical assessment using MATLAB/Simulink models. The simulation findings demonstrate the efficiency of the control approach to optimally manage the hybrid power generation device in distinct power generation and load demand situations. The writers of [20] reported hybrid generation of PV / FC energy; FC operation was based on the electrolyzer scheme. The authors in [21], proposed a hybrid WT/PC/ultra-capacitor system for stand-alone applications. A variety of wind velocity, solar radiation and load demand circumstances test the dynamic conduct of the suggested hybrid scheme. An advance power management scheme can be implemented to enhance the system performance. The motive of the above literature review is to add study news to the design of an advanced PV/WT/FC hybrid energy management scheme. Furthermore, the transient investigation of amalgamation WT/PV/FC power system is carried out for performance improvement by designing a simple and effective power management scheme.

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2 SYSTEM DESCRIPTION AND UNIT SIZING

2.1 System description
The system description for the suggested hybrid RE scheme is shown in the Fig. 1. The system consists of (i) PV system (a) Fuzzy logic controlled MPPT method (b) DC-DC solar boost converter (ii) WECS (a) Fuzzy logic controlled blade pitch angle controller (b) AC-DC converter (iii) Proton exchange membrane fuel cell (PEMFC) (a) Fuzzy logic controlled reactants flow pressure controller (b) DC-DC FC boost converter (iv) Dump load (v) Variable DC load.

The following idea is implemented before the debate on the unit size to indicate the general effectiveness and accessibility of a RE source [22]. Capacity factor ($K_c$) of used RE source is given as,

$$K_c = \frac{P_{act}}{P_{rated}}$$

(1)

where, $P_{act}$ is the average current production over a time period and $P_{rated}$ is the RE source power evaluation. The objective is to minimize the distinction between energy produced ($P_{gen}$) and demand power. The aim is to minimize the difference between the generated power ($P_{dem}$) and the demand power over a fixed time period [24].

$$\Delta P = P_{act} \times P_{dem}$$

$$= K_{cf_{_WT}} \times P_{WT_{_rated}} + K_{cf_{_PV}} \times P_{PV_{_rated}} - P_{dem}$$

(2)

Where, $P_{PV_{_rated}}$ is the power ranking of PV array and $P_{WT_{_rated}}$ is the WT power capacity. Similarly, the $K_{cf_{_PV}}$ and $K_{cf_{_WT}}$ are the capacity factors of PV and WT array respectively. The rated power for the PV scheme is conveyed to balance energy generation and demand using Eq. (3) as,

$$P_{PV_{_rated}} = \frac{P_{dem} \times K_{cf_{_WT}} \times P_{WT_{_rated}}}{K_{cf_{_PV}}}$$

(3)

Fig. 2, it can be observed that the load demand (average) is 2.3 kW. Then accordingly to the Eq. (3), the PV array size is evaluated to be as 1506.35W. The system component parameters are shown in Table 1.

<table>
<thead>
<tr>
<th>Table 1</th>
<th>System Component Parameters</th>
</tr>
</thead>
<tbody>
<tr>
<td>Solar PV array</td>
<td>Rated power 1506.35 W</td>
</tr>
<tr>
<td>Module rating</td>
<td>50W(21.55V×2.32A) @ STC</td>
</tr>
<tr>
<td>No. of modules (SP)</td>
<td>10 × 3 = 30 modules</td>
</tr>
<tr>
<td>WECS</td>
<td>Rated Power 1528 W</td>
</tr>
<tr>
<td>Rated torque</td>
<td>-19 Nm</td>
</tr>
<tr>
<td>Cut-in speed</td>
<td>3 m/s</td>
</tr>
<tr>
<td>Cut-out speed</td>
<td>24 m/s</td>
</tr>
<tr>
<td>PEMFC System</td>
<td>Stack power 1209 W</td>
</tr>
<tr>
<td>Single FC voltage</td>
<td>0.631 V</td>
</tr>
<tr>
<td>No. FCs in stack</td>
<td>337</td>
</tr>
</tbody>
</table>

3 MODELING OF SYSTEM
The modeling of various system components are detailed in this section.

3.1 Modeling of FLC based MPPT assisted PV system
3.1.1 Modeling of PV system
The PV frames are produced up of a mixture of blended and parallel PV cells, usually in Fig. 3 by the corresponding circuit as,
PV system cell voltage ($V_c$) is mainly based on cell temperature and the load present in Eq. (4) as,

$$V_c = \frac{AI_T}{e} \ln \left( \frac{I_{ph} + I_o - I_c}{I_o} \right) - R_c I_c$$

(4)

The $C_{TV}$ and $C_{TI}$ temperature coefficients for $V$ and $I$ are shown by Eq. (5)-(6) respectively.

$$C_{TV} = 1 + \beta_T (T_a - T_s)$$

(5)

$$C_{TI} = 1 + \frac{\gamma_T}{S_c} (T_s - T_a)$$

(6)

Correction coefficients factors ($C_{SV}$ and $C_{SI}$) are given in Eq. (7)-(8) as,

$$C_{SV} = 1 + \beta_T \alpha_s (S_s - S_c)$$

(7)

$$C_{SI} = 1 + \frac{1}{S_c} (S_s - S_c)$$

(8)

The $V_{cx}$ and $I_{phx}$ are expressed by Eq. (9)-(10),

$$V_{cx} = C_{TV} C_{SV} V_c$$

(9)

$$I_{phx} = C_{TI} C_{SI} I_{ph}$$

(10)

Using Eq. (4)-(10), modelling of PV system is done in MATLAB/Simulink GUI environment.

### 3.1.2 Fuzzy logic controlled MPPT method

The fuzzification, rule base, inference and de-fuzzification are main components of FLC [24], as shown in Fig. 4 as,

**Fig. 4 FLC-based MPPT method block diagram**

Error (E) and change of error (CE) are defined in Eq. (11) and (12) as,

$$Error(n) = \frac{Power_{pv}(n) - Power_{pv}(n-1)}{Voltage_{pv}(n) - Voltage_{pv}(n-1)}$$

(11)

$$ChangeError(n) = Error(n) - Error(n-1)$$

(12)

The Input and output variables membership functions are shown in Fig. 5(a)-(c) as,

**Fig. 5(a)-(c) Membership function of FLC based MPPT method**

The used rule base (RB) are shown in Table 2 as,

**TABLE 2**

<table>
<thead>
<tr>
<th>Rule Base for Duty Cycle Control</th>
</tr>
</thead>
<tbody>
<tr>
<td>NL</td>
</tr>
<tr>
<td>NM</td>
</tr>
<tr>
<td>NS</td>
</tr>
<tr>
<td>ZE</td>
</tr>
<tr>
<td>PS</td>
</tr>
<tr>
<td>PM</td>
</tr>
<tr>
<td>PL</td>
</tr>
</tbody>
</table>

### 3.2 Modeling of WECS

#### 3.2.1 Modeling of WT

WT is a mechanical energy that converts wind power. A WT can operate with the changeable angle and tip rate ratio (TSR) at a constant speed to generate constant energy [25]. The wind power is same to the quantity of per second energy produced. The mechanical power of WT is given by Eq. (13) as,

$$P_m = 0.5 \rho \pi R^2 C_p(\lambda, \beta)V_w^3$$

(13)

The $C_p$ is expressed and calculated from Eq. (14) and (15) as,
\[ C_p(\lambda, \beta) = C_1 \left( \frac{C_2 - C_3 \beta - C_4}{\lambda^2} \right) e^{\frac{-C_5}{\lambda}} + C_6 \lambda \]  
(14)

\[ \frac{1}{\lambda} = \frac{1}{\lambda + 0.08 \beta - \frac{0.035}{\beta^2 + 1}} \]  
(15)

\[ \lambda = \omega R / V_w \]  
(16)

Where, \( \omega \) is the rotor speed (rad/s). The \( C_p \) (efficiency coefficient) is the element of the energy obtained by WT from the complete power.

### 3.2.2 Modeling of permanent synchronous generator

The PMSGs are used for a variety of business applications. Usually PMSG converts WT's mechanical output into power for the scheduled system. Eq. (17) and (18) gives the PMSG mathematical model [24] as,

\[ \frac{di_d}{dt} = \frac{\left(-R_i i_d + \omega_c (L_{wi} + L_{di}) i_d + u_d\right)}{L_{di} + L_{wi}} \]  
(17)

\[ \frac{di_d}{dt} = \frac{\left(-R_i i_d + \omega_c (L_{wi} + L_{di}) i_d + u_d\right)}{L_{di} + L_{wi}} \]  
(18)

The generator rotor speed (\( \omega_c \)) (rad/s) and EM torque (\( \tau_{em} \)) are given in Eq. (19) and (20) as,

\[ \omega_c = p \omega \]  
(19)

\[ \tau_{em} = 1.5 p ((L_{di} - L_{wi}) i_d i_d + i_d \psi_f) \]  
(20)

### 3.2.3 Blade pitch angle controller

Error and Change Error are given in Eq. (21) and (22) as,

\[ Error(n) = \tau(n) - \tau(n - 1) \]  
(21)

\[ \text{ChangeError}(n) = Error(n) - Error(n - 1) \]  
(22)

The rule base (25 rules) considered in this controller, is shown in Table 3 as,

### TABLE 3

<table>
<thead>
<tr>
<th>Membership Functions</th>
<th>NB</th>
<th>NS</th>
<th>ZE</th>
<th>PS</th>
<th>PB</th>
</tr>
</thead>
<tbody>
<tr>
<td>( E/CE )</td>
<td>NB</td>
<td>NB</td>
<td>NS</td>
<td>NS</td>
<td>ZE</td>
</tr>
<tr>
<td>( \text{NB} )</td>
<td>NS</td>
<td>NS</td>
<td>ZE</td>
<td>PS</td>
<td>PB</td>
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<tr>
<td>( \text{PS} )</td>
<td>NB</td>
<td>ZE</td>
<td>PS</td>
<td>PS</td>
<td>PB</td>
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<tr>
<td>( \text{PB} )</td>
<td>ZE</td>
<td>PS</td>
<td>PS</td>
<td>PB</td>
<td>PB</td>
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</tbody>
</table>

For FLC design, the shift in the pitch angle (\( d\beta \)) is the error “E” and error “CE” of the WT torque and output. With this obtained pitch angle, WT optimal torque is achieved. The features input-output are depicted in the Fig. 6(a)-(c) as,

### 3.3 Modeling of fuel cell system

#### 3.3.1 Proton exchange membrane fuel cell

The FC voltage \( (V_{fc}) \), at any occurrence could be represented by Eq. (23). Nernst voltage \( (E) \) (Without load voltage) is decreased by three types of voltage drop classifications as,

\[ V_{fc} = E - V_{act} - V_{conc} - V_{ohm} \]  
(23)

The Nernst equation (NE) is represented in Eq. (24) [30] as,

\[ E = E_0 + \left( \frac{RT}{2F} \right) \ln \left( \frac{P_{H_2}}{P_{H_2O}} \right)^{\frac{1}{2}} \]  
(24)

The activation decrease can be shown by the Tafel’s expression in Eq. (25) that decreases the activation voltage \( V_{act} \) as,

\[ V_{act} = -0.9514 + 0.00312T - 0.00018T \left[ \ln (I) \right] + 7.4 \times 10^{-5}T \left[ \ln (\text{Conc} O_2) \right] \]  
(25)

The Conc. \( O_2 \) (oxygen concentration) is expressed as a function of FC temperature and \( O_2 \) pressure in Eq. (26) as,
\[ \text{Conc.}O_2 = \frac{Po_2}{5.08 \times 10^6 \times \exp \left( \frac{-498}{T} \right)} \]  

(26)

The voltage drop is almost linear in nature and ohmic \( V_{\text{ohm}} \). Membrane resistance \( R_{\text{mem}} \) is determined by separating \( t_m \) by conductivity \( \sigma \left( k \Omega^{-1} \text{cm}^{-1} \right) \), are shown in Eq. (27) and (28) as,

\[ V_{\text{ohm}} = IR_{\text{mem}} \]  

(27)

\[ R_{\text{mem}} = \frac{t_m}{\sigma} \]  

(28)

The cell potential reduces quickly at greater present densities owing to mass limits. The linearity is called the concentration of potential and is expressed in Eq. (29) [28] as,

\[ V_{\text{conc}} = c_1 - c_2(T - 273)e^{(c_f)} \]  

(29)

Here the coefficients \( c_1, c_2 \) and \( c_3 \) and Eq. (23)-(29) could be analysed for cell potential.

### 3.3.2 \( \text{H}_2 \) and \( \text{O}_2 \) flow rate controller

A FLC is used to control the reactants \( (\text{H}_2 \& \text{O}_2) \) flow pressure of the PEMFC. In the FLC, \( E \) and \( CE \) are considered as input variables and molar flow rate as output as shown in Fig. 7 [29]. Both the \( E \) and \( CE \) can be obtained in sample time using Eq. (30) - (31) as,

\[ \text{Error}(n) = \text{Power}_{rj}(n) - \text{Power}_{as},(n) \]  

\[ \text{ChangeError}(n) = \text{error}(n) - \text{error}(n - 1) \]  

(30)  

(31)

The membership function of \( E \), \( CE \) and reactant molar flow rate \( m_{H_2} \) are shown in Fig. 8(a)-(c) and fuzzy RB depicted in Table 4 as,

![Fig. 7(a)-(c). Membership functions](image)

<table>
<thead>
<tr>
<th>( E/\text{CE} )</th>
<th>( \text{NB} )</th>
<th>( \text{NS} )</th>
<th>( \text{ZE} )</th>
<th>( \text{PS} )</th>
<th>( \text{PB} )</th>
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<td>( \text{NS} )</td>
<td>( \text{ZE} )</td>
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<tr>
<td>( \text{NS} )</td>
<td>( \text{NB} )</td>
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<td>( \text{NS} )</td>
<td>( \text{ZE} )</td>
<td>( \text{PS} )</td>
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<tr>
<td>( \text{ZE} )</td>
<td>( \text{NS} )</td>
<td>( \text{ZE} )</td>
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<td>( \text{PS} )</td>
<td>( \text{PB} )</td>
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<td>( \text{PS} )</td>
<td>( \text{NS} )</td>
<td>( \text{ZPS} )</td>
<td>( \text{PS} )</td>
<td>( \text{PS} )</td>
<td>( \text{PB} )</td>
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<tr>
<td>( \text{PB} )</td>
<td>( \text{ZE} )</td>
<td>( \text{PS} )</td>
<td>( \text{PS} )</td>
<td>( \text{PB} )</td>
<td>( \text{PB} )</td>
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</tbody>
</table>

The authors in [30] proposed that suitable value of hydrogen is 2.617 times that of \( \text{O}_2 \) and the optimal factor is achieved as 2.608 for PEMFC operation. In this controller, both reactants are controlled simultaneously by using this relation in FLC.

### 4 POWER MANAGEMENT SYSTEM

The general power management approach among distinct energy sources is required for optimum use. WECS is controlled by a photovoltaic device and a controller of blade angles controlled by a highest surveillance point. In addition, the flow pressure controller for reactants \( (\text{H}_2 \& \text{O}_2) \) is intended for effective and precise FC operation under variable demand force. The energy difference between the sources and the demand for load is calculated and expressed in Eq. (32) as,

\[ P_{\text{net}} = P_{\text{WT}} + P_{\text{PV}} - P_{\text{Load}} - P_{\text{Dump}} \]  

(32)

where, \( P_{\text{WT}} \) is the WECS generated power, \( P_{\text{load}} \) is the load demand, \( P_{\text{PV}} \) is the PV system power and \( P_{\text{Dump}} \) is the dump power. The principal power management strategy is that, whenever excess power is generated by PV and WECS system \( (P_{\text{net}}>0) \); it is directed towards the dump load. Hence, the power balance equation can be expressed in Eq. (33) as,

\[ P_{\text{WT}} + P_{\text{PV}} = P_{\text{Load}} + P_{\text{Dump}} \]  

(33)

When there is insufficiency in generated power \( (P_{\text{net}}<0) \); the FC system starts to generate the required power to meet the load demand. Eq. (34) can express the power balance as,

\[ P_{\text{WT}} + P_{\text{PV}} + P_{\text{FC}} = P_{\text{Load}} \]  

(34)

where, \( P_{\text{FC}} \) is the FC system power produced.

The flow chart of the considered power management strategy is shown in Fig. 8 as,
5 RESULTS AND DISCUSSION

Studies were performed using separate load demand to check system efficiency under different circumstances. The findings achieved validate the model of the simulation as,

- Characteristics of the PV, WT and FC system
- Analysis of PV system
- Analysis of WT system
- Analysis of FC system
- Analysis with power management scheme in various load demands

5.1 Characteristics of the PV, WT and FC system

The Performance curves of the PV, WT and FC system are depicted in Fig. 9(a)-(c). Fig. 9(a) shows the P-V and I-V characteristic of the designed PV system for changing irradiation level which is step varied in the range 400-1000W/m². Due to change in irradiation level, the PV output V, I and P are analyzed to vary in the range 8-21.55V, 1.7-2.32A and 13.6-50W respectively.

Fig. 9(b) shows the $C_p - \lambda$ curve for variable $\beta$ ($0^\circ-16^\circ$) of the designed PMSG assisted WT system. It is evident from the curve that maximum value of $C_p$ i.e. 0.48 is achieved at $\lambda$ =8 and minimum value of $\beta$ i.e.$0^\circ$. The polarization curve of PEMFC depicting various voltage drops is shown in Fig. 9(c).

Fig. 9 Flow chart of the power management scheme for the proposed hybrid RE system
Single PEMFC voltage is observed to be 0.631V.

5.2 Characteristics of the PV, WT and FC system
The production voltage, present and energy of the PV scheme supported by the MPPT technique based on the FLC are shown in Fig. 10 as,

Fig. 10 Voltage, current and power of FLC based MPPT assisted PV system

In the Fig. 10 For FLC-based MPPT-PV scheme with irradiance levels of 1000 W / m², working temperature 25 °C is observed 215.51V, 6.99A and 1506.35W, respectively.

5.3 Performance analysis of WT system
The performance of blade pitch angle controller assisted WECS is analyzed under changed wind speed conditions. The wind speed is varied randomly 10-12.5 m/sec (range), shown in Fig. 11 as,

Fig. 11 Variation of wind speed (m/s)

As the wind speed varies in the above specified pattern, the output of WT torque (τWT) changes. This change in WT torque is adjusted by the blade pitch angle controller by varying β as shown in Fig. 12(a)-(b). The reference value of τWT is taken as -19 Nm and the variation of τWT and β is reported to in the range -18.69 to -19.23 Nm and 2 to 8.107° respectively.

5.4 Performance analysis of FC system
In Fig. 14, 2122.3V, 5.7A and 1209.71W are displayed the output V, I and P of the designed FC system as,

Fig. 14 PEMFC voltage, current and power at fixed reactants flow pressure

5.5 Performance analysis of FC system
For variable power demand circumstances from case I to VIII, the performance of the suggested electricity management aided generation system is analyzed as,

Case-I: Initially the P_demand is set at 800W. From Fig. 15, the status of the switches S1, S2, S3 and S4 is found to be 1, 0, 0 and 1 accordingly. The PV system is switched ON, WECS and FC are switched ‘ON’ and loading is ON. The Pextra / P_dump and Preq are computed 706.35 W, 0 W accordingly.
Case-II: At \( t = 1 \) sec, the \( P_{\text{demand}} \) is step increased to 1600 W. Due to this change in \( P_{\text{demand}} \) the status of the switches \( S_1, S_2, S_3 \) and \( S_4 \) changes to 1, 1, 0 and 1 accordingly. The PV system, WECS and dump load are turned ON and FC system is still turned switched OFF. The \( P_{\text{extra}} / P_{\text{dump}} \) is found 1434.35 W and \( P_{\text{req}} \) is 0 W.

Case-III: Now at \( t = 2 \) sec, \( P_{\text{demand}} \) is step changed to 2800 W but the status of the switches \( S_1, S_2, S_3 \) and \( S_4 \) is unchanged. The \( P_{\text{extra}} \) reduces to 234.35 W and \( P_{\text{req}} \) is unchanged as 0W.

Case-IV: Further, at \( t = 3 \) sec, \( P_{\text{demand}} \) is varied to 4000 W. Because of this variation in \( P_{\text{demand}} \) the power management scheme updates the status of the switches \( S_1, S_2, S_3 \) and \( S_4 \) to 1, 1, 1 and 0. The PV system, WECS and PEMFC systems are turned ON and dump load is turned OFF. The \( P_{\text{extra}} \) is reported to be 0 W and \( P_{\text{req}} \) is 965.65 W.

Case-V: Moreover, at \( t = 4 \) sec, \( P_{\text{demand}} \) is raised to 4200 W. The new status of all switches \( S_1, S_2, S_3 \) and \( S_4 \) remain unchanged, \( P_{\text{extra}} \) is observed to be 0 W and \( P_{\text{req}} \) is 1165.65 W.

Case-VI: Furthermore, at \( t = 5 \) sec, \( P_{\text{demand}} \) is step varied (reduced) to 2755 W. To compensate this change in \( P_{\text{demand}} \) the status of the switches \( S_1, S_2, S_3 \) and \( S_4 \) is updated to 1, 1, 0 and 1 respectively. The PV system, WECS and dump load are turned ON and PEMFC system is turned OFF. The \( P_{\text{extra}} \) is reported to be 279.35 W and \( P_{\text{req}} \) is 0W.

Case-VII: At \( t = 6 \) sec, \( P_{\text{demand}} \) is further step decreased to 1400 W. As a result of this variation in \( P_{\text{demand}} \), the status of all the switches \( S_1, S_2, S_3 \) and \( S_4 \) is updated to 1, 0, 0 and 1 respectively. The PV system and dump load are turned ON and WECS, FC systems are turned OFF. The \( P_{\text{extra}} \) is observed to be 106.35 W and \( P_{\text{req}} \) is 0 W.

Case-VIII: Finally at \( t = 7 \) sec, \( P_{\text{demand}} \) is further step decreased to 800 W. The status of the switches \( S_1, S_2, S_3 \) and \( S_4 \) remain unchanged as previous case-VII. The \( P_{\text{extra}} \) and \( P_{\text{req}} \) are observed to be 706.35 W and 0 W respectively.

It is evident from the Fig. 16 that \( P_{\text{PV}} \) and \( P_{\text{WT}} \) are 1506.35 W and 1528 W respectively. The value of \( P_{\text{FC}} \) and \( P_{\text{dump}} \) are found for varying in the range 0-1217 W and 0-1434.35 W respectively. Fig. 17 shows the variation of \( P_{\text{H}_2} \) and \( P_{\text{O}_2} \) needed for the demanded power by the FC system. The maximum demanded value of \( P_{\text{H}_2} \) (0-8.1 atm.) is three time \( P_{\text{O}_2} \) value as observed 0- 21.2 atm.
6. CONCLUSION

A stand-alone dc-linked RE-based PV/WT/FC scheme is suggested in this document. The setup of the system and its unit size are explained; the features of the principal parts of the scheme are acquired: PV/WT/FC systems. The WT and PV systems are the primary generation sources of energy and FC systems that supply energy to the system under energy deficit circumstances are power back-up sources. The suggested MATLAB/Simulink model of the hybrid scheme has been created. The transient system analysis was examined at variable load. In addition, the overall strategy for energy management for the proposed hybrid energy system is developed for the ideal application of different RE sources. The energy management system is tested in a number of instances and general output is satisfactory.

APPENDIX

Operating parameters of PEMFC, PV, WT and PMSG systems

<table>
<thead>
<tr>
<th>Operating parameters of PEMFC</th>
<th>Operating parameters of PV</th>
</tr>
</thead>
<tbody>
<tr>
<td>Curve fitting factor, ( k )</td>
<td>1.4</td>
</tr>
<tr>
<td>Boltzmann constant, ( \hat{k} )</td>
<td>1.38x10^-25 J/K</td>
</tr>
<tr>
<td>Cell temperature, ( T_c )</td>
<td>45°C</td>
</tr>
<tr>
<td>Electron charge, ( e )</td>
<td>1.602x10^-19 Coulombs</td>
</tr>
<tr>
<td>Series resistance, ( R_s )</td>
<td>0.037 ( \Omega )</td>
</tr>
<tr>
<td>Number of blades</td>
<td>3</td>
</tr>
<tr>
<td>Blade radius (R)</td>
<td>4.5m</td>
</tr>
<tr>
<td>Gear ratio (G)</td>
<td>40</td>
</tr>
<tr>
<td>Pitch angle (β)</td>
<td>Adjusted pitch</td>
</tr>
<tr>
<td>Wind speed (( \nu_w ))</td>
<td>10-18 m/sec</td>
</tr>
<tr>
<td>Tip speed ratio (A)</td>
<td>9</td>
</tr>
<tr>
<td>Power Coefficient (( C_p ))</td>
<td>0.45</td>
</tr>
<tr>
<td>( C_1, C_2, C_3 )</td>
<td>0.5176, 116, 4</td>
</tr>
<tr>
<td>( C_4, C_5, C_6 )</td>
<td>5, 21, 0.0068</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>WT operating parameters</th>
</tr>
</thead>
<tbody>
<tr>
<td>Stator Phase Resistance (( R_s ))</td>
</tr>
<tr>
<td>Inductance (( L_1, L_2 ))</td>
</tr>
<tr>
<td>Inertia (( J_1 ))</td>
</tr>
<tr>
<td>Friction factor (F)</td>
</tr>
<tr>
<td>No. of pole</td>
</tr>
<tr>
<td>Rated torque (( T_e ))</td>
</tr>
<tr>
<td>Rated voltage &amp; current</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>PMSG operating parameters</th>
</tr>
</thead>
<tbody>
<tr>
<td>Number of electrons, (n)</td>
</tr>
<tr>
<td>Mass of ( H_2 ), ( m_{H_2} )</td>
</tr>
<tr>
<td>Mass of ( O_2 ), ( m_{O_2} )</td>
</tr>
</tbody>
</table>

REFERENCES


[10] Trifkovic M, Sheikhzadeh M, Nigam K. Modeling and control of renewable hybrid energy system with hydrogen...


